System Dynamics (22.554 & 24.509)

Homework Assignment #5 -- Spring 2014

Transfer Function View of LTI Systems

Problem #1: Matrix Exponential via Laplace Transforms

Compute the matrix exponential for the following system matrix using the Laplace transform approach, where

$$\mathbf{e}^{\underline{\mathbf{A}}\mathbf{t}} = \mathbf{L}^{-1} \left\{ \left(\mathbf{s}_{\underline{\mathbf{I}}} - \underline{\mathbf{A}} \right)^{-1} \right\} \qquad \text{and} \qquad \underline{\underline{\mathbf{A}}} = \begin{bmatrix} \mathbf{0} & \mathbf{0} & -\mathbf{1} \\ \mathbf{2} & \mathbf{1} & \mathbf{2} \\ -\mathbf{2} & \mathbf{0} & \mathbf{1} \end{bmatrix}$$

Be sure to show your work! Does your final result agree with the result from HW #2 where we used Sylvester's Theorem? Which approach is easier to apply?

Problem #2: Inverse Laplace Transforms

Take the inverse Laplace transform of the following functions:

a.
$$\frac{s+1}{(s+2)^2(s+3)}$$
 b. $\frac{s+2}{s^2+2s+5}$

Problem #3: System Transfer Function Matrix and System Response

Given the following linear time-invariant system

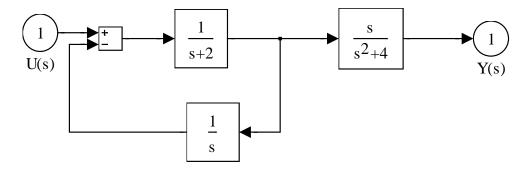
$$\frac{d}{dt}\underline{x}(t) = \underline{\underline{A}}\underline{x} + \underline{\underline{b}}u \qquad \text{with} \qquad \underline{\underline{y}}(t) = \underline{\underline{C}}\underline{x}(t)$$

where $\underline{\underline{A}} = \begin{bmatrix} 0 & 1 \\ 7 & -4 \end{bmatrix} \qquad \underline{\underline{b}} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \qquad \text{and} \qquad \underline{\underline{C}} = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$

- a. Analytically determine the system transfer function matrix.
- b. If u(t) is the unit step, what is $y_2(t)$? Answer this question using analytical means.
- c. Is this a stable system? Explain.
- d. Convert the state-space system to transfer function form using Matlab's **ss** and **tf** commands. Do you get the same transfer function matrix as in Part a? Now, simulate the system in Matlab and compare the analytical solution to $y_2(t)$ from Part b to the Matlab solution. Does everything make sense here?

Problem #4: Systems in Block Diagram Form

Consider the system shown below:



- a. Using block diagram arithmetic, determine the overall transfer function for this SISO system.
- b. Analytically determine the impulse response for this system using the transfer function, G(s), developed in Part a.
- c. Now create a transfer function object using Matlab's **tf** command starting with the G(s) result from Part a, and then determine the impulse response of this LTI transfer function object using the **impulse** command. Is your result the same as from Part b.
- d. Based on the results of Parts a and b, what is the order, n, of this SISO system?
- e. Convert the transfer function in Part a into an nth order ODE and put this into standard state form. This should be done by hand...
- f. Finally, within Matlab, convert the transfer function object from Part c into a state space object with the **ss** command. Does this system resemble your result from Part e? Do they have similar eigenvalues? Simulate both these state space systems to compare their impulse responses -- are they indeed identical? Explain your observations...

Documentation

Documentation for this assignment should include the hand manipulations needed for each problem, a listing of any requested Matlab script file and comparison plots, and a good description of your procedure and results for all the problems. As usual, an overall professional job is expected!