

Nuclear Reactor Theory

Lesson 0: Review of Some Key Concepts from Fundamentals of NSE

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ENGY.4340 Nuclear Reactor Theory
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(Sept. 2016)

Lesson 0 Objectives

Describe the terms **multiplication factor** and **reactivity**.

Describe the following **terms** and identify their **units**: **neutron density**, **neutron flux and current**, **microscopic and macroscopic cross sections**, **target atom densities**, and **neutron interaction rates**.

Explain the **general energy dependence**, $\sigma(E)$, of **typical cross sections**.

Write a **formal expression** for an **average multigroup cross section** and define what is meant by the phrase “**the scalar flux for group g**.”

Explain, in general terms, **how all the above items fit together** within the context of **steady-state reactor theory**.

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Some Terminology

Multiplication Factor: used to describe the state of the neutron balance in a nuclear system

$$\text{Rate of Change} = \text{Production Rate} - \text{Loss Rate}$$

$$k = \frac{\text{fissions in one generation}}{\text{fissions in preceding generation}}$$

$$= \frac{\text{fission neutrons in one generation}}{\text{fission neutrons in preceding generation}}$$

$$= \frac{\text{neutron production rate from fission}}{\text{neutron loss rate}}$$

$$k = \frac{\text{production}}{\text{absorption} + \text{leakage}}$$

- Critical** → production = absorption + leakage
Supercritical → production > absorption + leakage
Subcritical → production < absorption + leakage

Some Terminology (cont.)

Reactivity: measure of the deviation from critical

$$\rho = \frac{k-1}{k}$$

or

$$\rho = \frac{\text{production} - \text{loss}}{\text{production}}$$

When the neutron production and loss rates are in balance, then the neutron population remains constant or, in steady state, we have

for steady state

$$\text{Rate of Change} = \text{Production Rate} - \text{Loss Rate} = 0$$

external source
fission source
inscatter source

We need to describe these rates mathematically

leakage
absorption
outscatter

Reaction Rates

Recall that:

n = neutron density (neutrons/cm³)

v = neutron speed (cm/sec)

ϕ = neutron flux (neutrons/cm²-sec)

$$\phi = nv \quad \rightarrow \quad \frac{n}{\text{cm}^2 - \text{s}} = \left(\frac{n}{\text{cm}^3} \right) \left(\frac{\text{cm}}{\text{s}} \right)$$

N = target atom density (atoms/cm³)

σ_x = microscopic cross section (barns, where 1 b = 10⁻²⁴ cm²)
(measure of probability of interaction for reaction x)

$R = F$ = interaction rate density (reactions/cm³-sec)

$$R_x = N\sigma_x\phi \quad \rightarrow \quad \frac{\text{reactions}}{\text{cm}^3 - \text{s}} = \left(\frac{\text{atoms}}{\text{cm}^3} \right) (\text{cm}^2) \left(\frac{\text{neutrons}}{\text{cm}^2 - \text{s}} \right)$$

Reaction Rates (cont.)

Recall also that:

The term $N\sigma$ occurs so often that it is given the symbol, Σ , and called the **macroscopic cross section**.

For example,

$$\Sigma_t = N\sigma_t, \quad \Sigma_f = N\sigma_f, \quad \text{and} \quad \Sigma_c = N\sigma_c$$

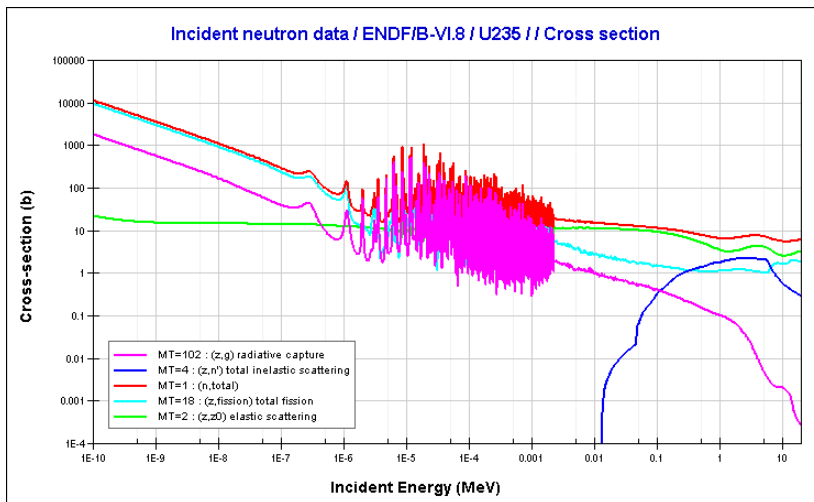
refer to the **macroscopic total**, **fission**, and **capture cross sections**, respectively.

These quantities have units of cm⁻¹ -- that is,

$$\Sigma_x = N\sigma_x \quad \rightarrow \quad \left(\frac{\text{atoms}}{\text{cm}^3} \right) (\text{cm}^2) = \left(\frac{\text{atoms}}{\text{cm}} \right) = \text{cm}^{-1}$$

Note, however, that the **cross sections** and **neutron flux** the are **strong functions of neutron energy**...

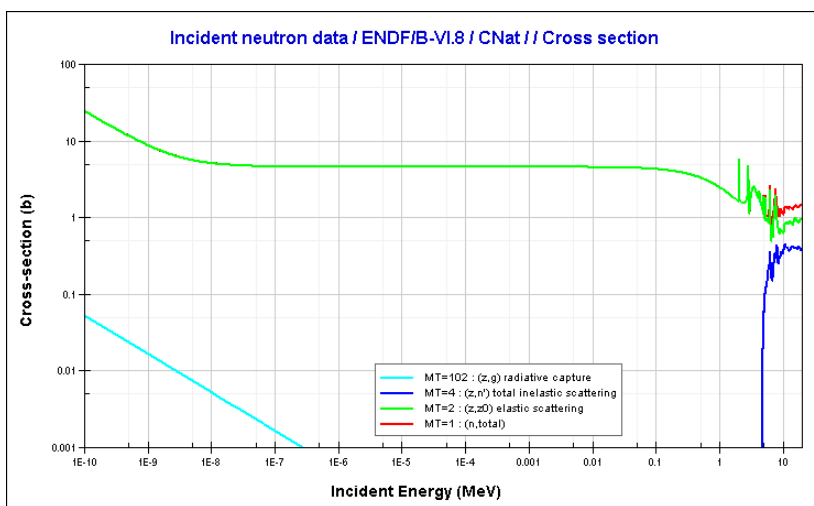
U235 Cross Sections



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Natural Carbon Cross Sections



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The Scalar Neutron Flux

As part of a practical **model reduction process**, we seek to simplify the full functional dependence of the **angular neutron flux**:

$$\phi(\vec{r}, \vec{v}, t) = n(\vec{r}, \vec{v}, t) v(E)$$

But, the **neutron velocity vector**, \vec{v} , can be written in terms of a **magnitude or speed**, v , and a **unit vector**, $\hat{\Omega}$, that points in the direction of neutron travel, or $\vec{v} = v\hat{\Omega}$.

Also, since $E = \frac{1}{2}mv^2$ for neutrons, we can interchange the dependence on v or E as desired.

Thus, the **angular flux** is usually written as

$$\phi(\vec{r}, E, \hat{\Omega}, t) = n(\vec{r}, E, \hat{\Omega}, t) v(E) \quad \text{angular neutron flux}$$

And the **scalar flux** is simply the **angular flux integrated over all angles**, or

$$\phi(\vec{r}, E, t) = \int_{\text{all angles}} \phi(\vec{r}, E, \hat{\Omega}, t) d\hat{\Omega} \quad \text{scalar neutron flux}$$

The Net Neutron Current

We will also need to discuss the flow of neutrons across a surface -- and the **neutron current**, \vec{J} , is used in these situations.

The **angular neutron current** is a **vector quantity** and it is defined in a similar fashion as the neutron flux, or

$$\vec{J}(\vec{r}, E, \hat{\Omega}, t) = n(\vec{r}, E, \hat{\Omega}, t) \vec{v}(E) \quad \text{angular neutron current}$$

But, $\vec{v} = v\hat{\Omega}$ and $\phi = nv$, so the **angular neutron current** can be written as

$$\vec{J}(\vec{r}, E, \hat{\Omega}, t) = \hat{\Omega} \phi(\vec{r}, E, \hat{\Omega}, t)$$

And the **net neutron current** is simply the **angular current integrated over all angles**, or

$$\vec{J}(\vec{r}, E, t) = \int_{\text{all angles}} \phi(\vec{r}, E, \hat{\Omega}, t) \hat{\Omega} d\hat{\Omega} = \int_{\text{all angles}} \vec{J}(\vec{r}, E, \hat{\Omega}, t) d\hat{\Omega} \quad \text{net neutron current}$$

ϕ and \vec{J} have the same units!!!

Multigroup Cross Sections & Flux



Now, in the **context of reactor physics applications**, we are interested in calculating **average multigroup cross sections** for use in solving the multigroup diffusion equation (**to be derived shortly**) for determining $\phi_g(\vec{r})$.

If we **denote Σ_g as the average value of $\Sigma(E)$ over energy interval ΔE_g** , then Σ_g is given by

$$\Sigma_g = \frac{\int_{\Delta E_g} \Sigma(E)\phi(E)dE}{\int_{\Delta E_g} \phi(E)dE} = \frac{1}{\phi_g} \int_{\Delta E_g} \Sigma(E)\phi(E)dE$$

average cross section in group g

where the group flux, ϕ_g , is given by

$$\phi_g = \int_{\Delta E_g} \phi(E)dE$$

scalar flux for group g

Putting It All Together



With an **estimate of $\phi(E)$** , we can **compute Σ_g** and, with knowledge of the **multigroup neutron balance equation**, we can **solve for $\phi_g(\vec{r})$** which allows determination of the **reaction rates, k_{eff}** , etc.

Thus, in the first part of this course -- **steady state reactor theory** (removes the time dependence) -- we will focus on the following:

1. Description of the **flux spectrum in thermal systems**. (Lesson #1)
2. Development of the **multigroup balance equation**. (Lesson #2)
3. **Solution of the diffusion equation** for several typical **subcritical and critical systems**. (Lessons #3 - #8)
4. Relationship of simple analytical treatment addressed here to **real-world computational reactor physics design and analysis** of actual reactor systems. (Lesson #9)

So let's do it...

Lesson 0 Summary



In this Lesson we have briefly reviewed the following subjects:

The terms **multiplication factor** and **reactivity**.

The following **terms** and their **units**: **neutron density**, **neutron flux and current**, **microscopic and macroscopic cross sections**, **target atom densities**, and **neutron interaction rates**.

The **general energy dependence**, $\sigma(E)$, of typical cross sections.

How to write a **formal expression** for an **average multigroup cross section** and what is meant by the phrase “**the scalar flux for group g** .”

How all the **above items fit together** within the study of **steady-state reactor theory**.